



Ocean Surface Topography Science Team Meeting

Precise Orbit Determination Splinter

JASON-2, JASON-3 and SENTINEL-3A/B POD STATUS

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PORTUGAL



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POE-F STANDARDS

	POE-E	POE-F
Surface forces	Atmospheric model : DTM-13 for Jason satellites, HY-2A , and MSIS-86 for other satellites	Atmospheric model : DTM-13 for Jason satellites, HY-2A , and MSIS-00 for other satellites
Geopotential	EIGEN-GRGS.RL03-v2.MEAN-FIELD C21/S21 modeled according to IERS 2010 conventions Ocean tides: FES2012 Atmospheric gravity: 6hr NCEP pressure fields (72x72) + tides from Biancale-Bode model	EIGEN-GRGS.RL04-v1.MEAN-FIELD C21/S21 non modified Ocean tides: FES2014 Atmospheric gravity: 3hr dealiasing products from GFZ AOD1B RL06
Geocenter	Seasonal non-tidal geocenter motion from J. Ries model for DORIS/SLR stations	Full non-tidal geocenter motion derived from DORIS data and the OSTM/Jason-2 satellite, for DORIS/SLR stations and GPS satellites

POE-F STANDARDS

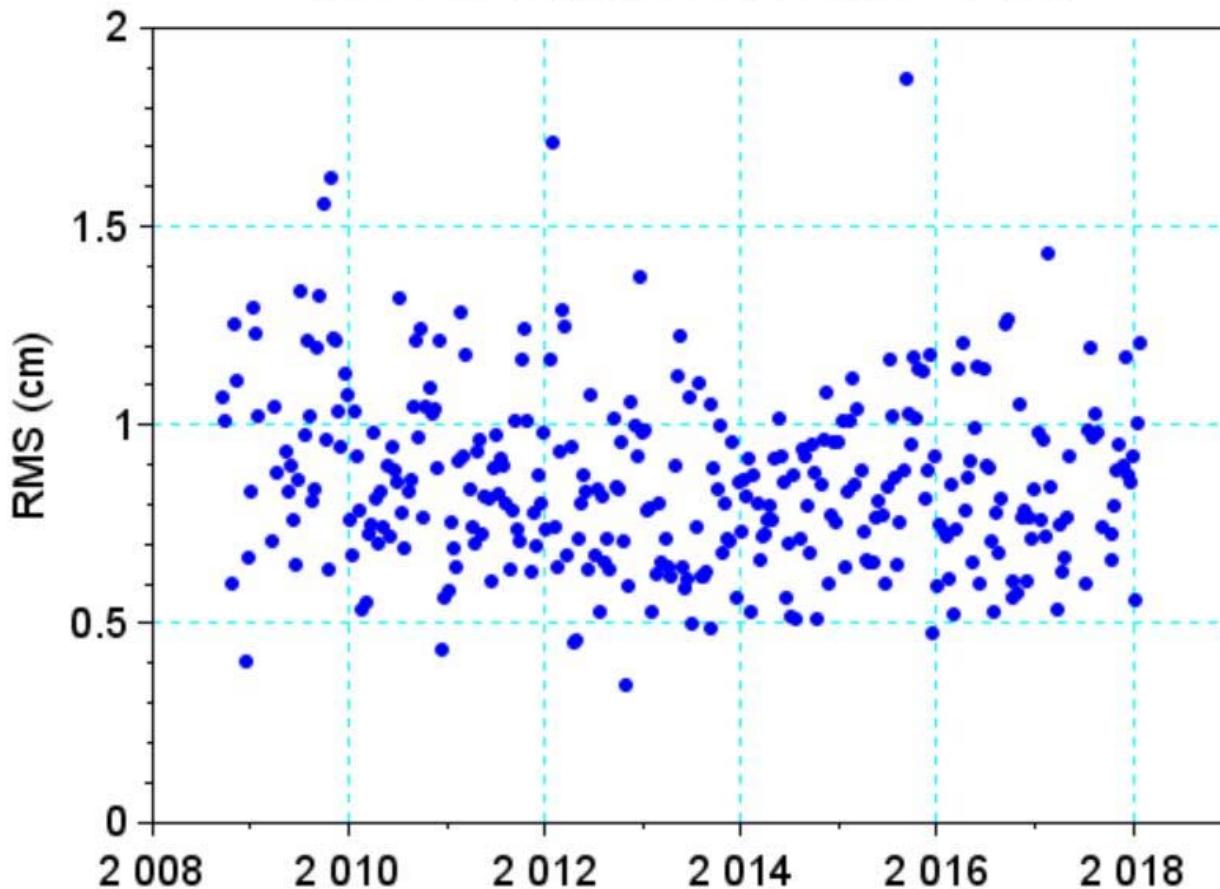
	POE-E	POE-F
<i>Loading</i>	Ocean loading: FES2012 Pole tide: solid earth pole tides and ocean pole tides (Desai, 2002) Mean pole cubic+linear (IERS 2010)	Ocean loading: FES2014 Pole tide: solid earth pole tides and ocean pole tides (Desai, 2002) New linear mean pole model
<i>GPS constellation</i>	JPL solution in “native” format (orbits and clocks), referenced to the CoM of the solid Earth/Ocean – fully consistent with IGS08	GRG solution with fixed ambiguity for JASON-3 SENTINEL-3A SENTINEL-3B – fully consistent with IGS14
<i>Propagation delay</i>	Tropospheric model GPT GMF	Tropospheric model GPT2 VMF1

POE-F STANDARDS

	POE-E	POE-F
Others	DORIS station coordinates in DPOD 2008 SLR coordinates stations in SLRF2008	DORIS station coordinates in DPOD 2014 SLR station coordinates in SLRF2014 Low elevation DORIS measurement (>5°) with weighting function and tropospheric gradients

JASON-2, POE-E standards, RMS SLR

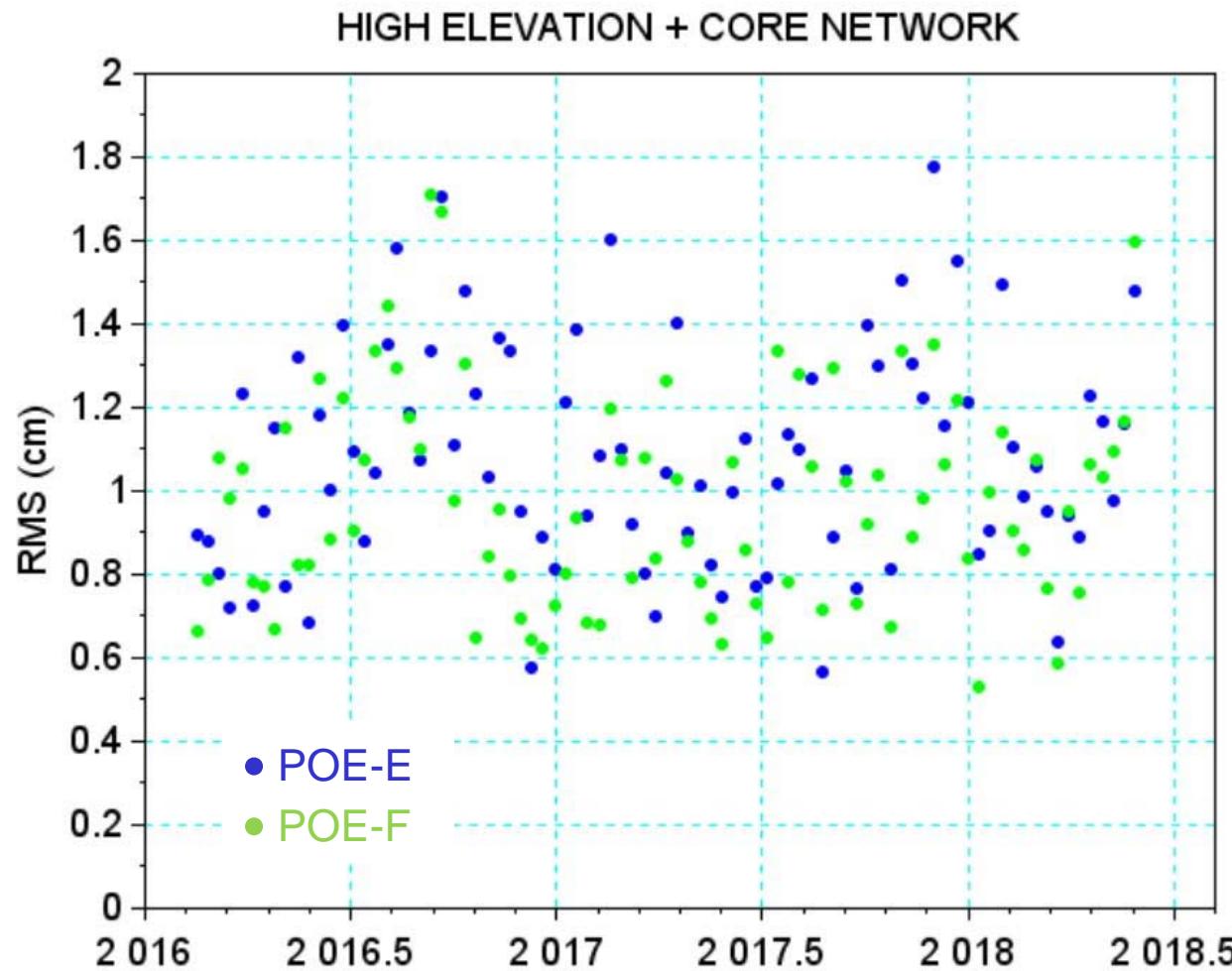
HIGH ELEVATION + CORE NETWORK



SLR CORE NETWORK
L7090 L7105 L7810 L7840 L7941

Stable time series for these RMS SLR,
with mean RMS 8mm

JASON-3, RMS SLR



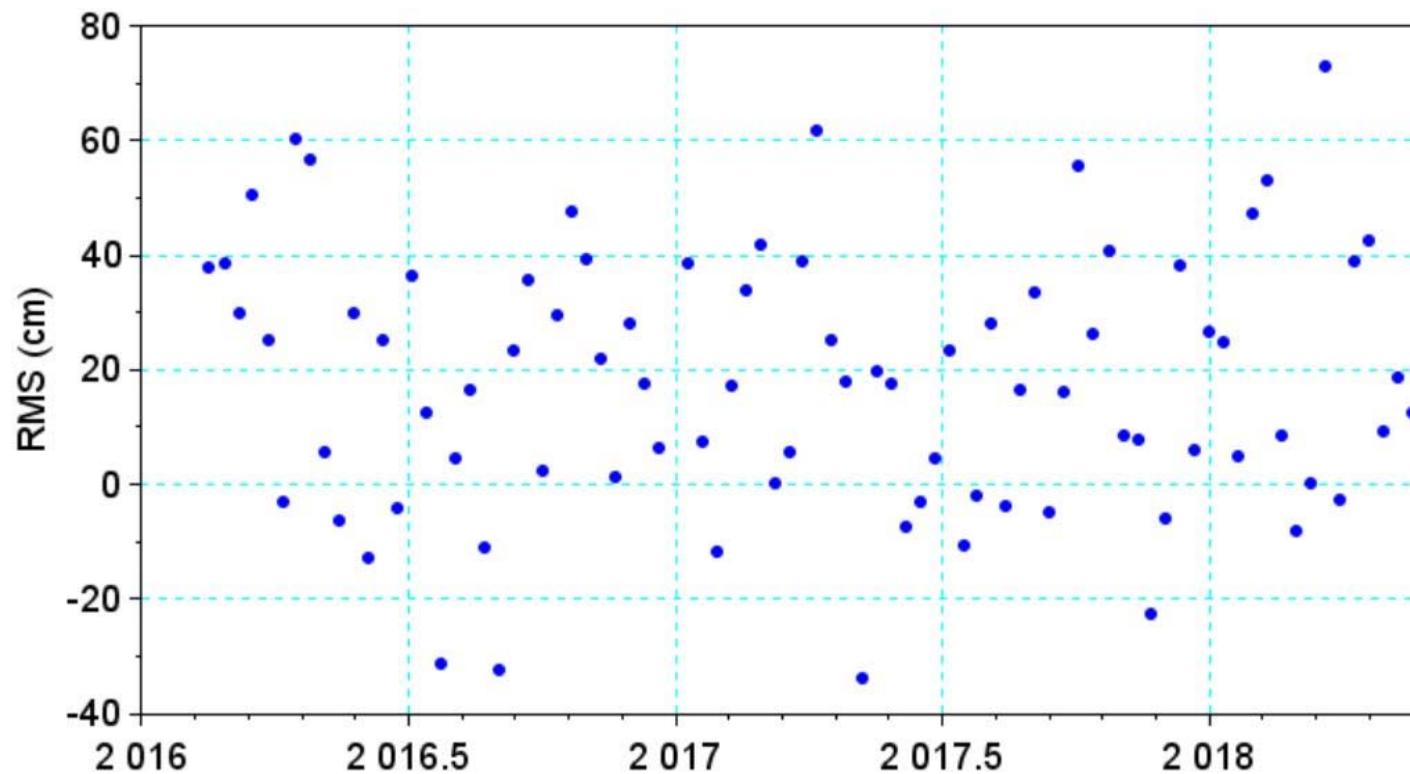
MEAN RMS SLR

POE-E 1.08cm

POE-F 0.97cm

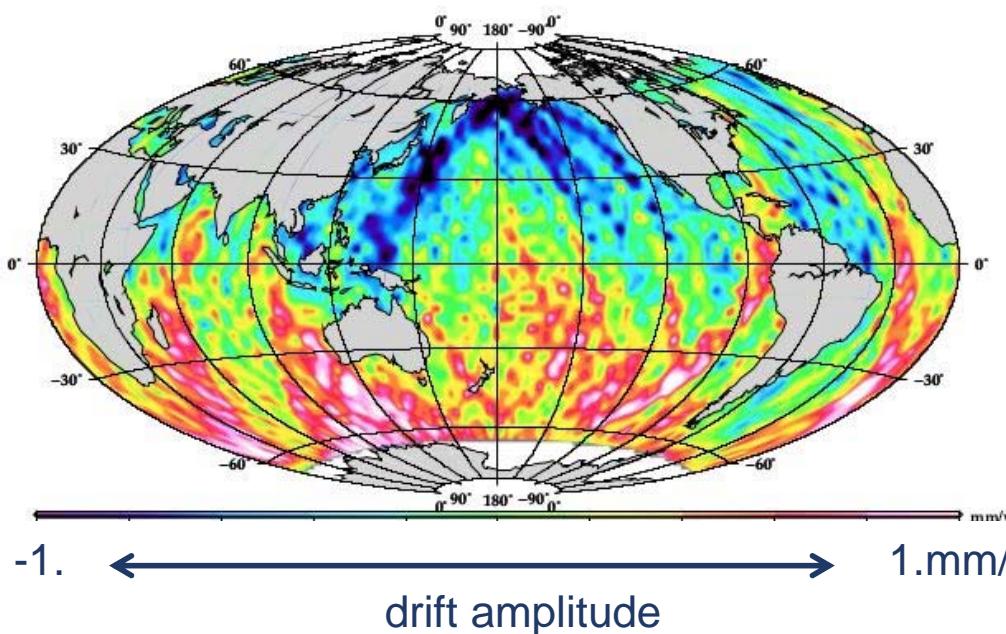
→ fixing ambiguities
c.f. poster & presentation of F.Mercier

JASON-3, CROSSOVER VARIANCE, POE-E vs POE-F

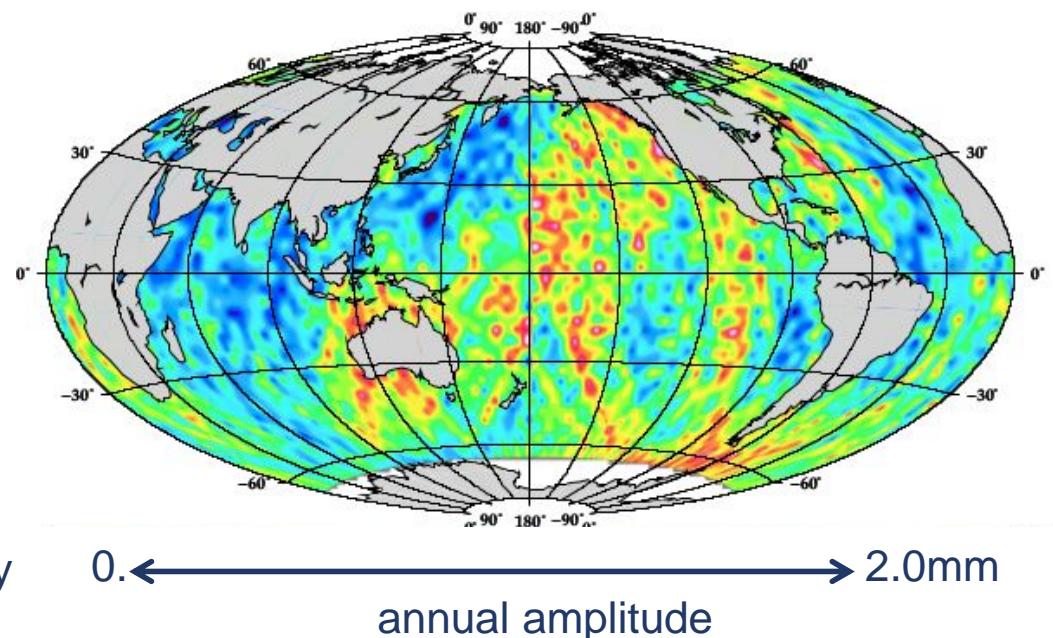


JASON-3, GEOGRAPHICALLY CORRELATED RADIAL DIFF.

POE-E vs POE-F, cycles 1→85



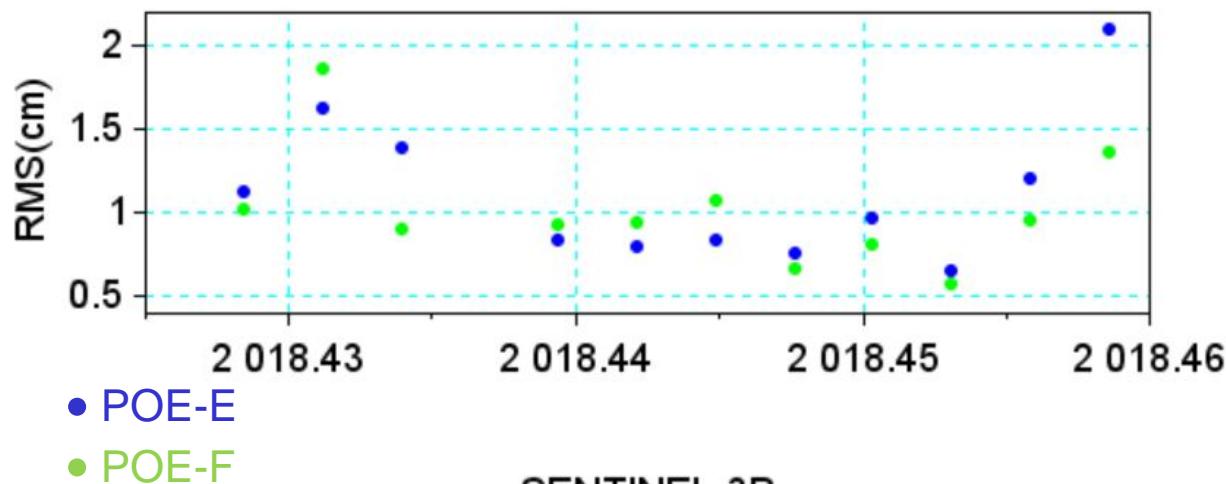
POE-E vs POE-F, cycles 1→85



Difference between POE-E and POE-F DORIS+GPS reduced dynamic orbits, patches north/south and west/east : combination of gravity field correction (sectorial terms) and geocenter motion ?

SENTINEL-3A/3B, RMS SLR CORE NETWORK

SENTINEL-3A

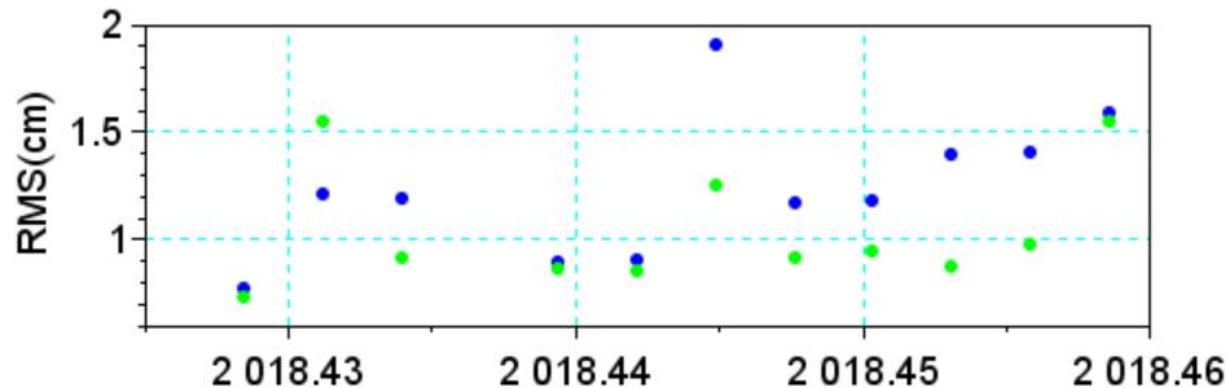


RMS BY DAYS, TANDEM PHASE FOR
SENTINEL-3A AND SENTINEL-3B

MEAN RMS SENTINEL-3A

POE-E 1.11cm
POE-F 1.00cm

SENTINEL-3B

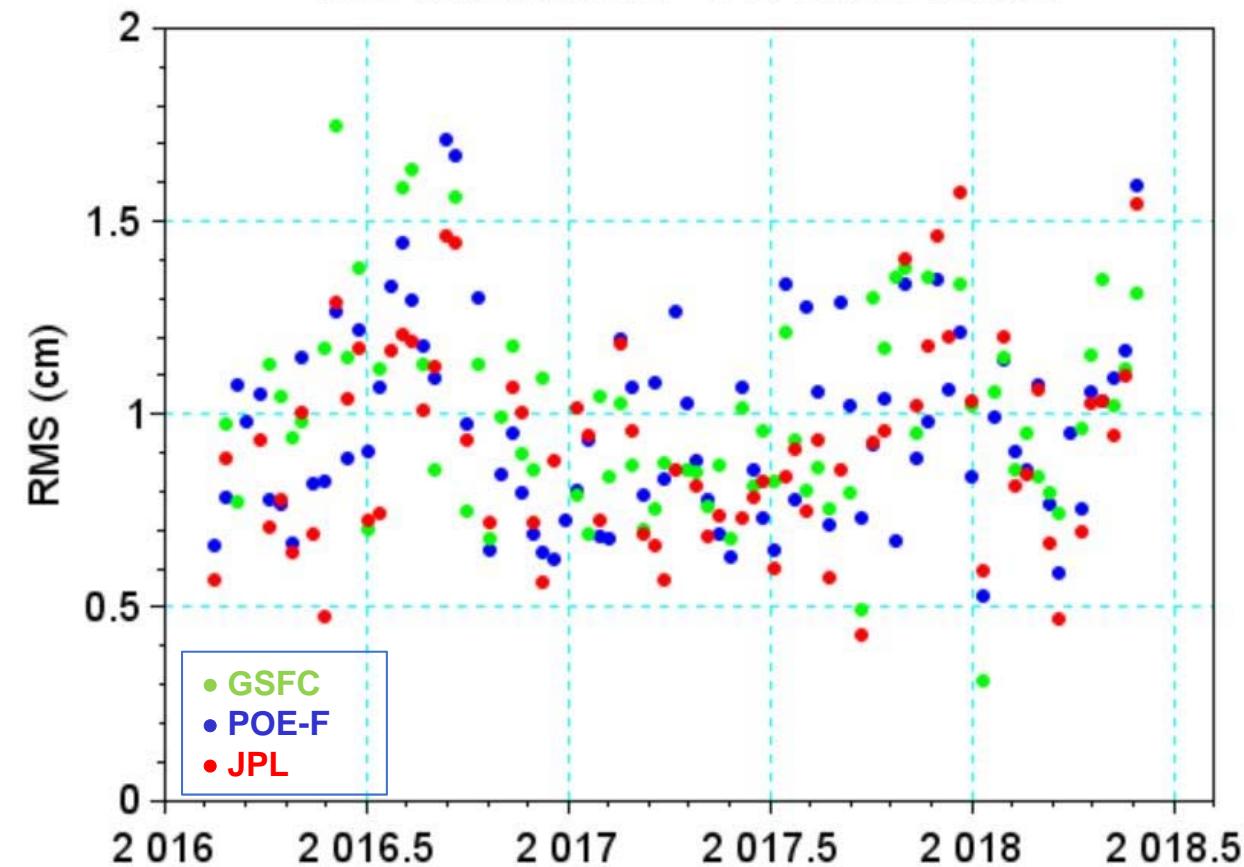


MEAN RMS SENTINEL-3B

POE-E 1.03cm
POE-F 0.80cm

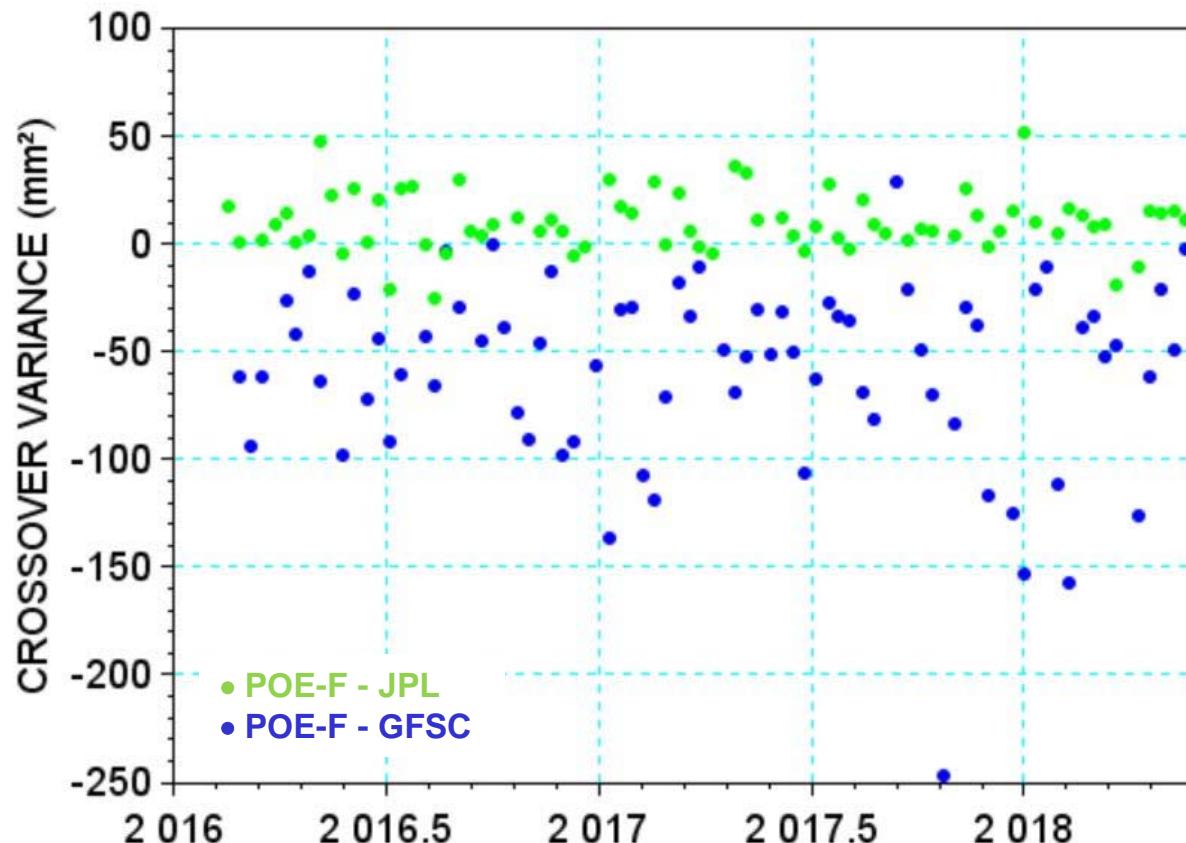
JPL & GSFC COMPARISONS, RMS SLR

HIGH ELEVATION + CORE NETWORK



HIGH ELEVATION + CORE NETWORK	DIFFERENCE RMS
POE-F – GSFC	-0.08 MM
POE-F – JPL	0.8 MM

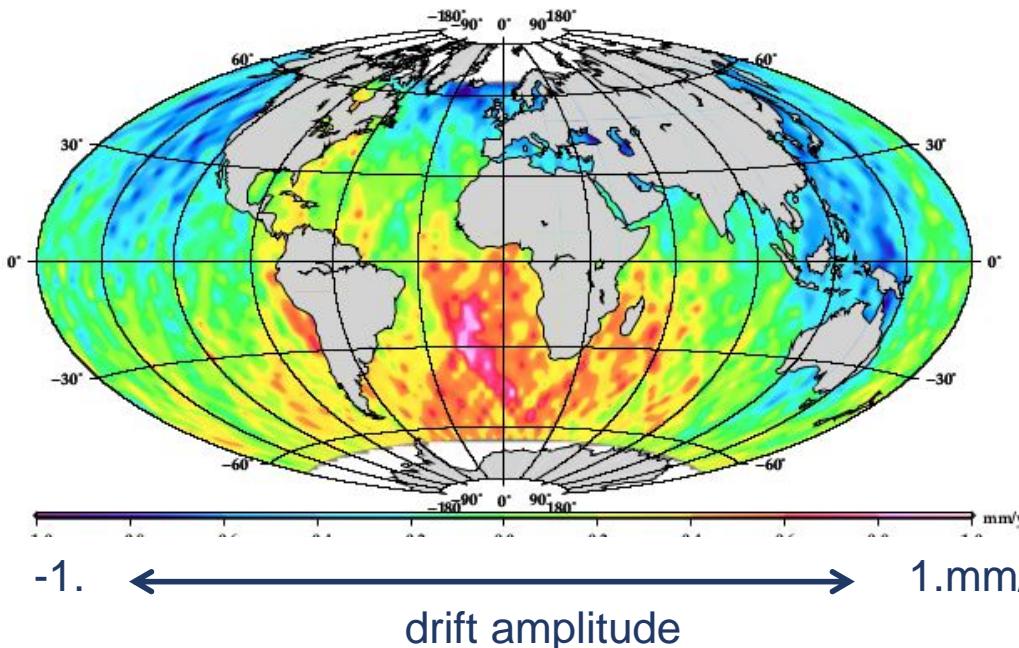
JPL & GSFC COMPARISONS, CROSSOVER VARIANCE



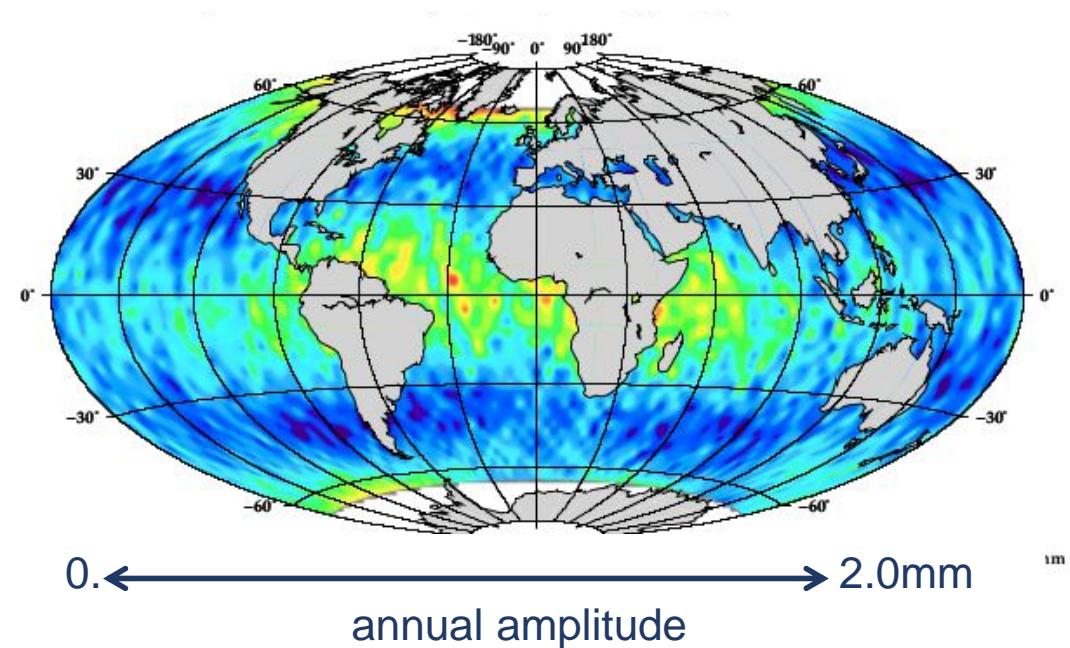
CROSSOVER VARIANCE DIFFERENCE	MEDIAN
POE-F – GSFC	-50 mm^2
POE-F – JPL	8 mm^2

JPL COMPARISONS, GEO. CORR. RADIAL DIFF.

POE-F vs JPL, cycles 1→85



POE-F vs JPL, cycles 1→85



PATCH NORTH / SOUTH : IMPACT OF MODELING GEOCENTER MOTION ?

PLANNED SWITCHS FROM POE-E TO POE-F

POE-F standard used in operational context :

- at the end of the tandem phase for SENTINEL-3A/B (first POE-F delivered in November this year)
- from cycle 95 for JASON-3 (first POE-F delivered in October this year)

Past orbits already reprocessed in POE-F for JASON-3

Reprocessing

TOPEX POSEIDON, in progress

JASON-2, beginning of 2019

CONCLUSION

POE-F standards show good improvements for JASON-3 and SENTINEL-3A/B

POE-F standards show improvements too for the TOPEX/Poseidon orbits, c.f. C. Masson's presentation

CNES POE-F JASON-3 and JPL orbits are very close

Operational switch from POE-E to POE-F for Sentinel-3A/B and JASON-3 is coming soon

... THANK YOU FOR YOUR ATTENTION , ANY QUESTIONS ? ...