

Variational Deep Learning-based interpolations of along-track Nadir and wide-swath SWOT altimetry observations

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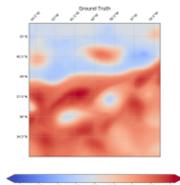
2020, October

- Ground truth dataset \mathbf{x} : high-resolution $1/60^\circ$ NATL60 configuration of the NEMO (Nucleus for European Modeling of the Ocean) model
- A $10^\circ \times 10^\circ$ GULFSTREAM region is used with down-graded resolution to $1/20^\circ$

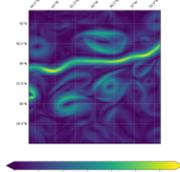
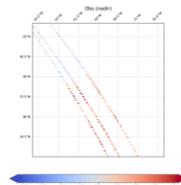
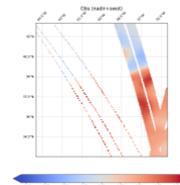


GULFSTREAM domain

- OSSE : pseudo-altimetric nadir and SWOT observational datasets $\mathbf{y} = \{\mathbf{y}_k\}$ at time t_k are generated by a realistic sub-sampling satellite constellations on subdomain $\Omega = \{\Omega_k\}$ of the grid.



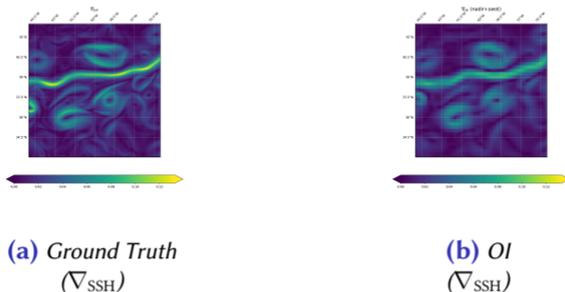
(a) Ground Truth (SSH)

(b) Ground Truth
(∇_{SSH})(c) Observations
(nadir)(d) Observations
(nadir+swot)

Ground Truth (SSH & ∇_{SSH}) and pseudo-observations (nadir & nadir+swot) on August 4, 2013

Methods

DUACS OI \bar{x} (Taburet et al.) as a baseline : significant smoothing, solving spatial scales up to 150km :



NATL60 & OI SSH and ∇_{SSH} on August 4, 2013

All the interpolations methods used here will work on the anomaly field $d\mathbf{x}$:

$$\mathbf{x} = \bar{\mathbf{x}} + d\mathbf{x} + \epsilon$$

Data-driven and learning-based approaches

- **VE-DINEOF** is a state-of-the-art interpolation approach (Ping et al., 2016) using an EOF-based iterative filling strategy. Typically the large-scale component provided by the OI is used (or 0 values if working on the anomaly) as a first guess to fill in the missing data over Ω ;
- **The Analog Data Assimilation (AnDA)** (Lguensat et al., 2017) is a purely data-driven data assimilation method introducing a statistical operator \mathcal{A} as a substitute for the dynamical model \mathcal{M} in a classic state-space formulation;
- **Convolutional Neural Networks (CNN)** : specifically dedicated to spatio-temporal interpolation problems (Fablet et al., 2019), neural DINEOF extensions + an explicit link with variational data assimilation

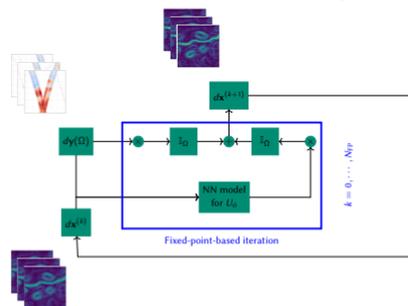
End-to-end learning

- An end-to-end learning representation has recently been introduced in Fablet et al. (2019) to deal with image sequences involving potentially large missing data rates. An energy-based representation $U_\psi = \|\mathbf{d}\mathbf{x} - \psi(\mathbf{d}\mathbf{x})\|_\Omega^2$ to minimize is introduced where the operator $\psi = \psi_\theta$ denotes a NN-based representation (Convolutional autoencoders **ConvAE** or Gibbs energy related NN **GENN**) of the underlying processes.
- For a specific definition of the hidden state interpolator $\widehat{\mathbf{d}\mathbf{x}}_k = I_{U_\psi}(\mathbf{d}\mathbf{y}_k(\Omega_k))$ based on the irregular space-time dataset $\{\mathbf{d}\mathbf{y}_k(\Omega_k)\}$, the learning problem for optimizing parameters θ of ψ is stated as the minimization of the reconstruction error :

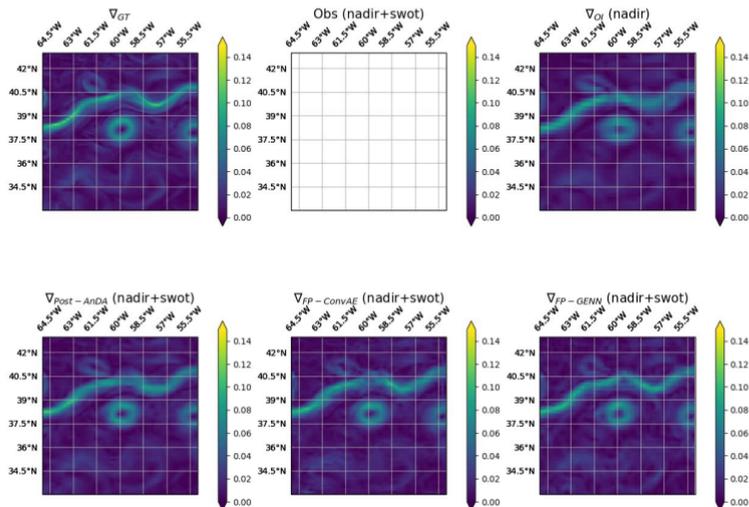
$$\hat{\theta} = \arg \min_{\theta} \sum_k \|\mathbf{d}\mathbf{y}_k(\Omega_k) - I_{U_\psi}(\mathbf{d}\mathbf{y}_k(\Omega_k))\|_{\Omega_k}^2$$

An iterative fixed-point (FP) solver is used to optimize parameters θ of the NN-model ψ w.r.t cost U_ψ :

$$\begin{cases} \mathbf{x}^{(i+1)} & = \psi(\mathbf{x}^{(i)}) \\ \mathbf{x}^{(i+1)}(\Omega) & = \mathbf{y}(\Omega) \\ \mathbf{x}^{(i+1)}(\overline{\Omega}) & = \mathbf{x}^{(i+1)}(\overline{\Omega}) \end{cases}$$



Sketch of the iterative fixed-point algorithm

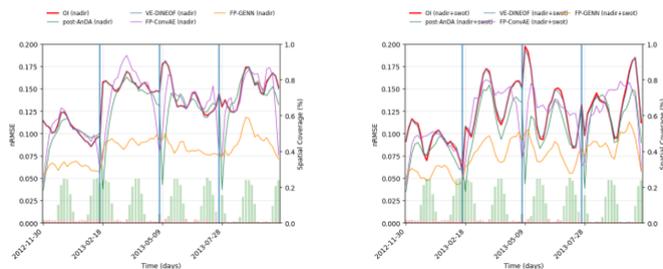


Global SSH gradient field reconstruction obtained for a joint assimilation/learning of along-track nadir with wide-swath SWOT data

Scores (I)

The scores are computed on four 20-day validation periods over the one-year NATL60 daily dataset :

Up to 40% relative gain on the SSH daily root mean squared error with FP-GENN
Up to 30% relative gain when using 2D SWOT vs 1D along-track nadir



(a) nadir

(b) nadir+swot

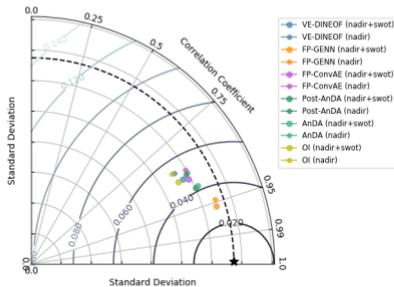
Daily spatial nRMSE computed on the 80-days non-continuous validation period. The spatial coverage of 0-days accumulated along-track nadir and wide-swath SWOT data are given by the red and green-colored barplots

Scores (II)

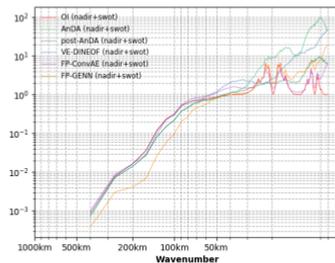
Reconstruction (R-)score (over Ω) and Interpolation (I-)score (over $\bar{\Omega}$)

FP-GENN always better on I-scores

Reconstruction of the spatial scales up to 50km which is an important improvement compared to the scales that OI is handling by now



(a) Taylor diagram



(b) Signal-to-noise ratio

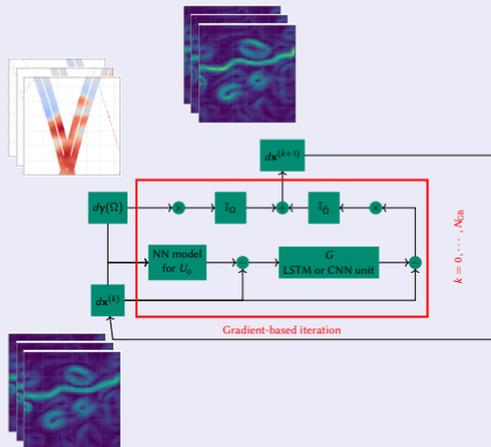
Taylor diagram and signal-to-noise ratio computed on the 80-days non-continuous validation period for a joint assimilation/learning with wide-swath SWOT data

Perspectives

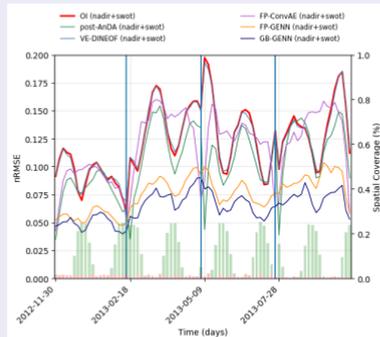
Replace the fixed-point solver by an iterative NN gradient-based descent to optimize parameters θ of the NN-model (ConvAE or GENN) ψ w.r.t cost U_ψ :

$$J_{U_\psi} = J_\psi(\mathbf{x})(\mathbf{x} - \psi(\mathbf{x})) \quad (4.1)$$

where J_{U_ψ} , the gradient of U_ψ , is finally replaced by a ConvNet or LSTM unit $G(\mathbf{x} - \psi(\mathbf{x}))$, thus enabling to solve jointly for the parametrization of ψ and G :



(a) Sketch of the iterative gradient-based algorithm



(b) nRMSE

Daily spatial nRMSE computed on the 80-days non-continuous validation period with gradient-based solver

References I

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